

NATURAL CONNECTIONS WITH TOTALLY SKEW-SYMMETRIC TORSION ON MANIFOLDS WITH NORDEN-TYPE METRICS

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Abstract. *This paper is a survey of results obtained by the authors on the geometry of connections with totally skew-symmetric torsion on the following manifolds: almost complex manifolds with Norden metric, almost contact manifolds with B-metric and almost hypercomplex manifolds with Hermitian and anti-Hermitian metric.*

Keywords: almost complex manifold, almost contact manifold, almost hypercomplex manifold, Norden metric, B-metric, anti-Hermitian metric, skew-symmetric torsion, KT-connection, HKT-connection, Bismut connection

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Introduction

In Hermitian geometry there is a strong interest in the connections preserving the metric and the almost complex structure whose torsion is totally skew-symmetric ([23, 24, 21, 1, 8, 9, 2, 3]). Such connections are called *KT-connections* (or *Bismut connections*). They find widespread application in mathematics as well as in theoretic physics. For instance, it is proved a local index theorem for non-Kähler manifolds by KT-connection in [1] and the same connection is applied in string theory in [21]. According to [8], on any Hermitian manifold, there exists a unique KT-connection. In [3] all almost contact, almost Hermitian and G_2 -structures admitting a KT-connection are described.

In this work¹ we provide a survey of our investigations into connections with totally skew-symmetric torsion on almost complex manifolds with Norden metric, almost contact manifolds with B-metric and almost hypercomplex manifolds with Hermitian and anti-Hermitian metric.

In Section 1 we consider an almost complex manifold with Norden metric (i.e. a neutral metric g with respect to which the almost complex structure J is an anti-isometry). On such a manifold we study a natural connection (i.e. a linear connection ∇' preserving J and g) and having totally skew-symmetric torsion. We prove that ∇' exists only when the manifold belongs to the unique basic class with non-integrable structure J . This is the class W_3 of quasi-Kähler manifolds with Norden metric. We establish conditions for the corresponding curvature tensor to be Kählerian as well as conditions ∇' to

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have a parallel torsion. We construct a relevant example on a 4-dimensional Lie group.

In Section 2 we consider an almost contact manifold with B-metric which is the odd-dimensional analogue of an almost complex manifold with Norden metric. On such a manifold we introduce the so-called φ KT-connection having totally skew-symmetric torsion and preserving the almost contact structure and the metric. We establish the class of the manifolds where this connection exists. We construct such a connection and study its geometry. We establish conditions for the corresponding curvature tensor to be of φ -Kähler type as well as conditions for the connection to have a parallel torsion. We construct an example on a 5-dimensional Lie group where the φ KT-connection has a parallel torsion.

In Section 3 we consider an almost hypercomplex manifold with Hermitian and anti-Hermitian metric. This metric is a neutral metric which is Hermitian with respect to the first almost complex structure and an anti-Hermitian (i.e. a Norden) metric with respect to the other two almost complex structures. On such a manifold we introduce the so-called pHKT-connection having totally skew-symmetric torsion and preserving the almost hypercomplex structure and the metric. We establish the class of the manifolds where this connection exists. We study the unique pHKT-connection D on a nearly Kähler manifold with respect to the first almost complex structure. We establish that this connection coincides with the known KT-connection on nearly Kähler manifolds and therefore it has a parallel torsion. We prove the equivalence of the conditions D be strong, flat and with a parallel torsion with respect to the Levi-Civita connection.

1. Almost complex manifold with Norden metric

Let (M, J, g) be a $2n$ -dimensional *almost complex manifold with Norden metric*, i.e. M is a differentiable manifold with an almost complex structure J and a pseudo-Riemannian metric g such that

$$J^2x = -x, \quad g(Jx, Jy) = -g(x, y)$$

for arbitrary x, y of the algebra $\mathfrak{X}(M)$ on the smooth vector fields on M . Further x, y, z, w will stand for arbitrary elements of $\mathfrak{X}(M)$.

The associated metric \tilde{g} of g on M is defined by $\tilde{g}(x, y) = g(x, Jy)$. Both metrics are necessarily of signature (n, n) . The manifold (M, J, \tilde{g}) is also an almost complex manifold with Norden metric.

A classification of the almost complex manifolds with Norden metric is given in [4]. This classification is made with respect to the tensor F of type $(0,3)$ defined by $F(x, y, z) = g((\nabla_x J)y, z)$, where ∇ is the Levi-Civita connection of g . The tensor F has the following properties

$$(1) \quad F(x, y, z) = F(x, z, y) = F(x, Jy, Jz), \quad F(x, Jy, z) = -F(x, y, Jz).$$

The basic classes are \mathcal{W}_1 , \mathcal{W}_2 and \mathcal{W}_3 . Their intersection is the class \mathcal{W}_0 of the Kählerian-type manifolds, determined by $\mathcal{W}_0 : F(x, y, z) = 0 \Leftrightarrow \nabla J = 0$.

The class \mathcal{W}_3 of the *quasi-Kähler manifolds with Norden metric* is determined by the condition

$$(2) \quad \mathcal{W}_3 : F(x, y, z) + F(y, z, x) + F(z, x, y) = 0.$$

This is the only class of the basic classes \mathcal{W}_1 , \mathcal{W}_2 and \mathcal{W}_3 , where each manifold (which is not a Kähler-type manifold) has a non-integrable almost complex structure J , i.e. the Nijenhuis tensor N , determined by $N(x, y) = (\nabla_x J) Jy - (\nabla_y J) Jx + (\nabla_{Jx} J) y - (\nabla_{Jy} J) x$ is non-zero.

The components of the inverse matrix of g are denoted by g^{ij} with respect to a basis $\{e_i\}$ of the tangent space $T_p M$ of M at a point $p \in M$.

The *square norm of ∇J* is defined by

$$\|\nabla J\|^2 = g^{ij} g^{ks} g((\nabla_{e_i} J) e_k, (\nabla_{e_j} J) e_s).$$

Definition 1. ([19]). An almost complex manifold with Norden metric and $\|\nabla J\|^2 = 0$ is called an *isotropic-Kähler manifold*.

1.1. KT-CONNECTION

Let ∇' be a linear connection on an almost complex manifold with Norden metric (M, J, g) . If T is the torsion tensor of ∇' , i.e. $T(x, y) = \nabla'_x y - \nabla'_y x - [x, y]$, then the corresponding tensor of type (0,3) is determined by $T(x, y, z) = g(T(x, y), z)$.

Definition 2. ([6]). A linear connection ∇' preserving the almost complex structure J and the Norden metric g , i.e. $\nabla' J = \nabla' g = 0$, is called a *natural connection* on (M, J, g) .

By analogy with Hermitian geometry we have given the following

Definition 3. ([16]). A natural connection ∇' on an almost complex manifold with Norden metric is called a *KT-connection* if its torsion tensor T is totally skew-symmetric, i.e. a 3-form.

We have proved the following

Theorem 1. ([18]). *If a KT-connection ∇' exists on an almost complex manifold with Norden metric then the manifold is quasi-Kählerian with Norden metric.*

A partial decomposition of the space \mathcal{T} of the torsion (0,3)-tensors T is valid on an almost complex manifold with Norden metric (M, J, g) according to [6]: $\mathcal{T} = \mathcal{T}_1 \oplus \mathcal{T}_2 \oplus \mathcal{T}_3 \oplus \mathcal{T}_4$, where \mathcal{T}_i ($i = 1, 2, 3, 4$) are invariant orthogonal subspaces.

Theorem 2. ([18]). *Let ∇' be a KT-connection with torsion T on a quasi-Kähler manifold with Norden metric $(M, J, g) \notin \mathcal{W}_0$. Then*

- 1) $T \in \mathcal{T}_1 \oplus \mathcal{T}_2 \oplus \mathcal{T}_4$;
- 2) T does not belong to any of the classes $\mathcal{T}_1 \oplus \mathcal{T}_2$ and $\mathcal{T}_1 \oplus \mathcal{T}_4$;
- 3) $T \in \mathcal{T}_2 \oplus \mathcal{T}_4$ if and only if T is determined by

$$(3) \quad T(x, y, z) = -\frac{1}{2}\{F(x, y, Jz) + F(y, z, Jx) + F(z, x, Jy)\}.$$

Bearing in mind that T is a 3-form, the following is valid

$$(4) \quad g(\nabla'_x y - \nabla_x y, z) = \frac{1}{2}T(x, y, z).$$

Then, by (4), (1) and (2), it follows directly that the tensor T , determined by (3), is the unique torsion tensor of a KT-connection, which is a linear combination of the components of the basic tensor F on (M, J, g) [22].

Further, the notion of the KT-connection ∇' on (M, J, g) we refer to the connection with the torsion tensor determined by (3).

1.2. KT-CONNECTION WITH KÄHLER CURVATURE TENSOR OR PARALLEL TORSION

Definition 4. ([5]). A tensor L is called a *Kähler tensor* if it has the following properties:

$$\begin{aligned} L(x, y, z, w) &= -L(y, x, z, w) = -L(x, y, w, z), \\ L(x, y, z, w) + L(y, z, x, w) + L(z, x, y, w) &= 0, \\ L(x, y, Jz, Jw) &= -L(x, y, z, w). \end{aligned}$$

Let R' be the curvature tensor of the KT-connection ∇' , i.e. $R'(x, y)z = \nabla'_x(\nabla'_y z) - \nabla'_y(\nabla'_x z) - \nabla'_{[x, y]}z$. The corresponding tensor of type $(0, 4)$ is determined by $R'(x, y, z, w) = g(R'(x, y)z, w)$.

We have therefore proved the following

Theorem 3. ([16]). *The following conditions are equivalent:*

- i) R' is a Kähler tensor;
- ii) $12R'(x, y, z, w) = 12R(x, y, z, w) + 2g(T(x, y), T(z, w)) - g(T(y, z), T(x, w)) - g(T(z, x), T(y, w))$;
- iii) $\mathfrak{S}_{x, y, z} \{g((\nabla_x J) Jy + (\nabla_{Jx} J) y, (\nabla_z J) Jw + (\nabla_{Jz} J) w)\} = 0$, where \mathfrak{S} denotes the cyclic sum by three arguments.

Proposition 4. ([16, 17]). *Let τ and τ' be the scalar curvatures for R and R' , respectively. Then the following is valid*

- i) $3\|\nabla J\|^2 = 8(\tau' - \tau)$ if ∇' has a Kähler curvature tensor;
- ii) $\|\nabla J\|^2 = 8(\tau - \tau')$ if ∇' has a parallel torsion.

Corollary 5. ([17]). *If ∇' has a Kähler curvature tensor and a parallel torsion then (M, J, g) is an isotropic-Kähler manifold.*

1.3. AN EXAMPLE

Let (G, J, g) be a 4-dimensional almost complex manifold with Norden metric, where G is the connected Lie group with an associated Lie algebra \mathfrak{g} determined by a global basis $\{X_i\}$ of left invariant vector fields, and J and g are the almost complex structure and the Norden metric, respectively, determined by

$$JX_1 = X_3, \quad JX_2 = X_4, \quad JX_3 = -X_1, \quad JX_4 = -X_2$$

and

$$g(X_1, X_1) = g(X_2, X_2) = -g(X_3, X_3) = -g(X_4, X_4) = 1, \\ g(X_i, X_j) = 0 \quad \text{for } i \neq j.$$

Theorem 6. ([18]). *The manifold (G, J, g) is a quasi-Kählerian with a Killing associated Norden metric \tilde{g} , i.e.*

$$g([X_i, X_j], JX_k) + g([X_i, X_k], JX_j) = 0,$$

if and only if \mathfrak{g} is defined by

$$\begin{aligned} [X_1, X_2] &= \lambda_1 X_1 + \lambda_2 X_2, & [X_1, X_3] &= \lambda_3 X_2 - \lambda_1 X_4, \\ [X_1, X_4] &= -\lambda_3 X_1 - \lambda_2 X_4, & [X_2, X_3] &= \lambda_4 X_2 + \lambda_1 X_3, \\ [X_2, X_4] &= -\lambda_4 X_1 + \lambda_2 X_3, & [X_3, X_4] &= \lambda_3 X_3 + \lambda_4 X_4, \end{aligned}$$

where $\lambda_1, \lambda_2, \lambda_3, \lambda_4 \in \mathbb{R}$.

Let (G, J, g) be the manifold determined by the conditions in the last theorem.

The non-trivial components $T_{ijk} = T(X_i, X_j, X_k)$ of the torsion T of the KT-connection ∇' on (G, J, g) are $T_{134} = \lambda_1$, $T_{234} = \lambda_2$, $T_{123} = -\lambda_3$, $T_{124} = -\lambda_4$.

Moreover it is proved the following

Theorem 7. ([18]). *The following propositions are equivalent:*

- i) *The manifold (G, J, g) is isotropic-Kählerian;*
- ii) *The manifold (G, J, g) is scalar flat;*
- iii) *The KT-connection ∇' has a Kähler curvature tensor;*
- iv) *The equality $\lambda_1^2 + \lambda_2^2 - \lambda_3^2 - \lambda_4^2 = 0$ is valid.*

2. Almost contact manifolds with B-metric

Let $(M, \varphi, \xi, \eta, g)$ be an almost contact manifold with B-metric (an almost contact B-metric manifold), i.e. M is a $(2n+1)$ -dimensional differentiable manifold with an almost contact structure (φ, ξ, η) which consists of an endomorphism φ of the tangent bundle, a vector field ξ , its dual 1-form η as well as M is equipped with a pseudo-Riemannian metric g of signature $(n, n+1)$,

such that the following algebraic relations are satisfied

$$\begin{aligned}\varphi\xi = 0, \quad \varphi^2 = -I + \eta \otimes \xi, \quad \eta \circ \varphi = 0, \quad \eta(\xi) = 1, \\ g(\varphi x, \varphi y) = -g(x, y) + \eta(x)\eta(y),\end{aligned}$$

where I denotes the identity.

Let us remark that the so-called B-metric g one can say a *metric of Norden type* in the odd-dimensional case, because the restriction of g on the contact distribution $\ker \eta$ is a Norden metric with respect to the almost complex structure derived by φ .

The associated metric \tilde{g} of g on M is defined by $\tilde{g}(x, y) = g(x, \varphi y) + \eta(x)\eta(y)$. Both metrics are necessarily of signature $(n, n + 1)$. The manifold $(M, \varphi, \xi, \eta, \tilde{g})$ is also an almost contact B-metric manifold.

A classification of the almost contact manifolds with B-metric is given in [7]. This classification is made with respect to the tensor F of type $(0,3)$ defined by $F(x, y, z) = g((\nabla_x \varphi) y, z)$, where ∇ is the Levi-Civita connection of g . The tensor F has the following properties

$$F(x, y, z) = F(x, z, y) = F(x, \varphi y, \varphi z) + \eta(y)F(x, \xi, z) + \eta(z)F(x, y, \xi).$$

This classification includes eleven basic classes $\mathcal{F}_1, \mathcal{F}_2, \dots, \mathcal{F}_{11}$. The special class \mathcal{F}_0 , belonging to any other class \mathcal{F}_i ($i = 1, 2, \dots, 11$), is determined by the condition $F(x, y, z) = 0$. Hence \mathcal{F}_0 is the class of almost contact B-metric manifolds with ∇ -parallel structures, i.e. $\nabla\varphi = \nabla\xi = \nabla\eta = \nabla g = 0$.

In the present work we pay attention to \mathcal{F}_3 and \mathcal{F}_7 , where each manifold (which is not a \mathcal{F}_0 -manifold) has a non-integrable almost contact structure, i.e. the Nijenhuis tensor N , determined by $N(x, y) = [\varphi, \varphi](x, y) + d\eta(x, y)\xi$, is non-zero. These basic classes are characterized by the conditions

$$\mathcal{F}_3 : \quad \underset{x, y, z}{\mathfrak{S}} F(x, y, z) = 0, \quad F(\xi, y, z) = F(x, y, \xi) = 0,$$

$$\mathcal{F}_7 : \quad \underset{x, y, z}{\mathfrak{S}} F(x, y, z) = 0, \quad F(x, y, z) = -F(\varphi x, \varphi y, z) - F(\varphi x, y, \varphi z).$$

Let us consider the linear projectors h and v over $T_p M$ which split (orthogonally and invariantly with respect to the structural group) any vector x into a horizontal component $h(x) = -\varphi^2 x$ and a vertical component $v(x) = \eta(x)\xi$.

The decomposition $T_p M = h(T_p M) \oplus v(T_p M)$ generates the corresponding distribution of basic tensors F , which gives the horizontal component \mathcal{F}_3 and the vertical component \mathcal{F}_7 of the class $\mathcal{F}_3 \oplus \mathcal{F}_7$.

The *square norm* of $\nabla\varphi$ is defined by

$$\|\nabla\varphi\|^2 = g^{ij}g^{ks}g((\nabla_{e_i}\varphi)e_k, (\nabla_{e_j}\varphi)e_s).$$

Definition 5. ([14]). An almost contact B-metric manifold with $\|\nabla\varphi\|^2=0$ is called an *isotropic- \mathcal{F}_0 -manifold*.

2.1. φ KT-CONNECTION

Definition 6. ([14]). A linear connection D preserving the almost contact B-metric structure (φ, ξ, η, g) , i.e. $D\varphi = D\xi = D\eta = Dg = 0$, is called a *natural connection* on $(M, \varphi, \xi, \eta, g)$.

Definition 7. ([14]). A natural connection D on an almost contact B-metric manifold is called a φ KT-connection if its torsion tensor T is totally skew-symmetric, i.e. a 3-form.

The following theorem is proved.

Theorem 8. ([14]). *If a φ KT-connection D exists on an almost contact B-metric manifold $(M, \varphi, \xi, \eta, g)$ then ξ is a Killing vector field and $\mathfrak{S}F = 0$, i.e. $(M, \varphi, \xi, \eta, g)$ belongs to the class $\mathcal{F}_3 \oplus \mathcal{F}_7$.*

The existence of a φ KT-connection D on a manifold in $\mathcal{F}_3 \oplus \mathcal{F}_7$ is given by the following

Proposition 9. ([14]). *Let $(M, \varphi, \xi, \eta, g)$ be in the class $\mathcal{F}_3 \oplus \mathcal{F}_7$. Then the connection D with a torsion tensor T , determined by*

$$(5) \quad T(x, y, z) = -\frac{1}{2} \mathfrak{S}_{x,y,z} \{F(x, y, \varphi z) - 3\eta(x)F(y, \varphi z, \xi)\},$$

is a φ KT-connection on $(M, \varphi, \xi, \eta, g)$.

Further, the notion of the φ KT-connection D on $(M, \varphi, \xi, \eta, g)$ we refer to the connection with the torsion tensor determined by (5). For this connection we have

$$D_x y = \nabla_x y + \frac{1}{4} \{2(\nabla_x \varphi) \varphi y - (\nabla_y \varphi) \varphi x + (\nabla_{\varphi y} \varphi) x + 3\eta(x) \nabla_y \xi - 4\eta(y) \nabla_x \xi + 2(\nabla_x \eta) y \cdot \xi\}.$$

2.2. THE φ KT-CONNECTION ON THE HORIZONTAL COMPONENT

Let us consider a manifold from the class \mathcal{F}_3 – the horizontal component of $\mathcal{F}_3 \oplus \mathcal{F}_7$. Since the restriction on the contact distribution of any \mathcal{F}_3 -manifold is an almost complex manifold with Norden metric belonging to the class \mathcal{W}_3 (known as a quasi-Kähler manifold with Norden metric), then the curvature properties are obtained in a way analogous to that in Section 1.

2.3. THE φ KT-CONNECTION ON THE VERTICAL COMPONENT

Let $(M, \varphi, \xi, \eta, g)$ belong to the class \mathcal{F}_7 – the vertical component of $\mathcal{F}_3 \oplus \mathcal{F}_7$. For such a manifold the torsion of the φ KT-connection D has the form

$$T(x, y) = 2\{\eta(x) \nabla_y \xi - \eta(y) \nabla_x \xi + (\nabla_x \eta) y \cdot \xi\}.$$

A *tensor of φ -Kähler type* we call a tensor with the properties from Definition 4 with respect to the structure φ .

We have proved the following

Theorem 10. ([14]). *The curvature tensor K of D on a \mathcal{F}_7 -manifold is of φ -Kähler type if and only if it has the form*

$$\begin{aligned} K(x, y, z, w) = & R(x, y, z, w) \\ & + \frac{1}{3} \{ 2 (\nabla_x \eta) y (\nabla_z \eta) w - (\nabla_y \eta) z (\nabla_x \eta) w - (\nabla_z \eta) x (\nabla_y \eta) w \} \\ & + \eta(x) \eta(z) g (\nabla_y \xi, \nabla_w \xi) - \eta(x) \eta(w) g (\nabla_y \xi, \nabla_z \xi) \\ & - \eta(y) \eta(z) g (\nabla_x \xi, \nabla_w \xi) + \eta(y) \eta(w) g (\nabla_x \xi, \nabla_z \xi). \end{aligned}$$

Theorem 11. ([14]). *If D has a curvature tensor K of φ -Kähler type and a parallel torsion T on a \mathcal{F}_7 -manifold then*

$$\begin{aligned} K(x, y, z, w) = & R(x, y, z, w) \\ & + \frac{1}{3} \{ 2 (\nabla_x \eta) y (\nabla_z \eta) w + (\nabla_x \eta) z (\nabla_y \eta) w - (\nabla_x \eta) w (\nabla_y \eta) z \}, \end{aligned}$$

$$\rho(K)(y, z) = \rho(y, z), \quad \tau(K) = \tau,$$

where $\rho(K)$ and ρ are the Ricci tensors for K and R , respectively, and $\tau(K)$ and τ are their corresponding scalar curvatures.

2.4. AN EXAMPLE

Let $(G, \varphi, \xi, \eta, g)$ be a 5-dimensional almost contact manifold with B-metric, where G is the connected Lie group with an associated Lie algebra \mathfrak{g} determined by a global basis $\{X_i\}$ of left invariant vector fields, and (φ, ξ, η) and g are the almost contact structure and the B-metric, respectively, determined by

$$\begin{aligned} \varphi X_1 = X_3, \quad \varphi X_2 = X_4, \quad \varphi X_3 = -X_1, \quad \varphi X_4 = -X_2, \quad \varphi X_5 = 0; \\ \xi = X_5; \quad \eta(X_i) = 0 \quad (i = 1, 2, 3, 4), \quad \eta(X_5) = 1; \end{aligned}$$

$$\begin{aligned} g(X_1, X_1) = g(X_2, X_2) = -g(X_3, X_3) = -g(X_4, X_4) = g(X_5, X_5) = 1, \\ g(X_i, X_j) = 0, \quad i \neq j, \quad i, j \in \{1, 2, 3, 4, 5\}. \end{aligned}$$

Theorem 12. ([14]). *The manifold $(G, \varphi, \xi, \eta, g)$ is a \mathcal{F}_7 -manifold if and only if \mathfrak{g} is determined by the following non-zero commutators:*

$$\begin{aligned} [X_1, X_2] = -[X_3, X_4] = -\lambda_1 X_1 - \lambda_2 X_2 + \lambda_3 X_3 + \lambda_4 X_4 + 2\mu_1 X_5, \\ [X_1, X_4] = -[X_2, X_3] = -\lambda_3 X_1 - \lambda_4 X_2 - \lambda_1 X_3 - \lambda_2 X_4 + 2\mu_2 X_5, \end{aligned}$$

where $\lambda_i, \mu_j \in \mathbb{R}$ ($i = 1, 2, 3, 4; j = 1, 2$).

Let $(G, \varphi, \xi, \eta, g)$ be the manifold determined by the conditions in the last theorem.

The non-trivial components $T_{ijk} = T(X_i, X_j, X_k)$ of the torsion T of the φ KT-connection D on $(G, \varphi, \xi, \eta, g)$ are $T_{125} = T_{345} = 2\mu_1$, $T_{235} = T_{415} = 2\mu_2$.

Hence, using the components of D , we calculate that the corresponding components of the covariant derivative of T with respect to D are zero. Thus, we have proved the following

Theorem 13. ([14]). *The φ KT-connection D on $(G, \varphi, \xi, \eta, g)$ has a parallel torsion T .*

Theorem 14. ([14]). *The manifold $(G, \varphi, \xi, \eta, g)$ is an isotropic- \mathcal{F}_0 -manifold if and only if $\mu_1 = \pm \mu_2$.*

3. Almost hypercomplex manifolds with Hermitian and Norden metric

Let (M, H) be an *almost hypercomplex manifold*, i.e. M is a $4n$ -dimensional differentiable manifold and $H = (J_1, J_2, J_3)$ is a triple of almost complex structures with the properties:

$$J_\alpha = J_\beta \circ J_\gamma = -J_\gamma \circ J_\beta, \quad J_\alpha^2 = -I$$

for all cyclic permutations (α, β, γ) of $(1, 2, 3)$.

The standard structure of H on a $4n$ -dimensional vector space with a basis

$$\{X_{4k+1}, X_{4k+2}, X_{4k+3}, X_{4k+4}\}_{k=0,1,\dots,n-1}$$

has the form:

$$\begin{aligned} J_1 X_{4k+1} &= X_{4k+2}, & J_2 X_{4k+1} &= X_{4k+3}, & J_3 X_{4k+1} &= -X_{4k+4}, \\ J_1 X_{4k+2} &= -X_{4k+1}, & J_2 X_{4k+2} &= X_{4k+4}, & J_3 X_{4k+2} &= X_{4k+3}, \\ J_1 X_{4k+3} &= -X_{4k+4}, & J_2 X_{4k+3} &= -X_{4k+1}, & J_3 X_{4k+3} &= -X_{4k+2}, \\ J_1 X_{4k+4} &= X_{4k+3}, & J_2 X_{4k+4} &= -X_{4k+2}, & J_3 X_{4k+4} &= X_{4k+1}. \end{aligned}$$

Let g be a pseudo-Riemannian metric on (M, H) with the properties

$$g(x, y) = \varepsilon_\alpha g(J_\alpha x, J_\alpha y), \quad \varepsilon_\alpha = \begin{cases} 1, & \alpha = 1; \\ -1, & \alpha = 2; 3. \end{cases}$$

In other words, for $\alpha = 1$, the metric g is Hermitian with respect to J_1 , whereas in the cases $\alpha = 2$ and $\alpha = 3$ the metric g is an anti-Hermitian (i.e. Norden) metric with respect to J_2 and J_3 , respectively. Moreover, the associated bilinear forms g_1, g_2, g_3 are determined by

$$g_\alpha(x, y) = g(J_\alpha x, y) = -\varepsilon_\alpha g(x, J_\alpha y), \quad \alpha = 1, 2, 3.$$

Then, we call a manifold with such a structure briefly an *almost (H, G) -manifold* [12, 13].

The structural tensors of an almost (H, G) -manifold are the three $(0, 3)$ -tensors determined by

$$F_\alpha(x, y, z) = g((\nabla_x J_\alpha) y, z) = (\nabla_x g_\alpha)(y, z), \quad \alpha = 1, 2, 3,$$

where ∇ is the Levi-Civita connection generated by g .

In the classification of Gray-Hervella [11] for almost Hermitian manifolds the class $\mathcal{G}_1 = \mathcal{W}_1 \oplus \mathcal{W}_3 \oplus \mathcal{W}_4$ is determined by the condition $F_1(x, x, z) = F_1(J_1x, J_1x, z)$.

Theorem 15. ([15]). *If M is an almost (H, G) -manifold which is a quasi-Kähler manifold with Norden metric regarding J_2 and J_3 , then it belongs to the class \mathcal{G}_1 with respect to J_1 .*

3.1. PHKT-CONNECTION

Definition 8. ([15]). A linear connection D preserving the almost hypercomplex structure H and the metric g , i.e. $DJ_1 = DJ_2 = DJ_3 = Dg = 0$, is called a *natural connection* on (M, H, G) .

Definition 9. ([15]). A natural connection D on an almost (H, G) -manifold is called a *pseudo-HKT-connection* (briefly, a *pHKT-connection*) if its torsion tensor T is totally skew-symmetric, i.e. a 3-form.

For an almost complex manifold with Hermitian metric (M, J, g) , in [3] it is proved that there exists a unique KT-connection if and only if the Nijenhuis tensor $N_J(x, y, z) := g(N_J(x, y), z)$ is a 3-form, i.e. the manifold belongs to the class of cocalibrated structures \mathcal{G}_1 .

3.2. THE CLASS \mathcal{W}_{133}

Next, we restrict the class $\mathcal{G}_1(J_1)$ to its subclass $\mathcal{W}_1(J_1)$ of *nearly Kähler manifolds with neutral metric* regarding J_1 defined by $F_1(x, y, z) = -F_1(y, x, z)$. In this case (M, H, G) belongs to the class $\mathcal{W}_{133} = \mathcal{W}_1(J_1) \cap \mathcal{W}_3(J_2) \cap \mathcal{W}_3(J_3)$ and $\dim M \geq 8$.

We have proved the following

Theorem 16. ([15]). *The curvature tensor R of ∇ on $(M, H, G) \in \mathcal{W}_{133}$ has the following property with respect to the almost hypercomplex structure H :*

$$R(x, y, z, w) + \sum_{\alpha=1}^3 R(x, y, J_\alpha z, J_\alpha w) = \sum_{\alpha=1}^3 \{A_\alpha(x, z, y, w) - A_\alpha(y, z, x, w)\},$$

where $A_\alpha(x, y, z, w) = g((\nabla_x J_\alpha) y, (\nabla_z J_\alpha) w)$, $\alpha = 1, 2, 3$.

3.3. THE PHKT-CONNECTION ON A \mathcal{W}_{133} -MANIFOLD

KT-connections on nearly Kähler manifolds are investigated for instance in [20]. The unique KT-connection D^1 for the nearly Kähler manifold (M, J_1, g) on the considered almost (H, G) -manifold has the form

$$g(D_x^1 y, z) = g(\nabla_x y, z) + \frac{1}{2} F_1(x, y, J_1 z).$$

Moreover, there exists a unique KT-connection D^α ($\alpha = 2, 3$) for the quasi-Kähler manifold with Norden metric (M, J_α, g) on the considered almost (H, G) -manifold such that

$$g(D_x^\alpha y, z) = g(\nabla_x y, z) - \frac{1}{4} \mathfrak{S}_{x,y,z} F_\alpha(x, y, J_\alpha z).$$

In [15] we have constructed a connection D , using the KT-connections D^1 , D^2 and D^3 , on an almost (H, G) -manifold from the class \mathcal{W}_{133} and we have proved the following

Theorem 17. ([15]). *The connection D defined by*

$$g(D_x y, z) = g(\nabla_x y, z) + \frac{1}{2} F_1(x, y, J_1 z).$$

is the unique pHKT-connection on an almost (H, G) -manifold from the class \mathcal{W}_{133} .

Let us remark that the pHKT-connection D on an almost (H, G) -manifold coincides with the known KT-connection D^1 on the corresponding nearly Kähler manifold. Then the torsion of the pHKT-connection D is parallel and henceforth T is coclosed, i.e. $\delta T = 0$ [3]. Moreover, the curvature tensors K of D and R of ∇ has the following relation [10]

$$K(x, y, z, w) = R(x, y, z, w) + \frac{1}{4} A_1(x, y, z, w) + \frac{1}{4} \mathfrak{S}_{x,y,z} A_1(x, y, z, w).$$

We have proved the following

Theorem 18. ([15]). *Let (M, H, G) be an almost (H, G) -manifold from \mathcal{W}_{133} and D be the pHKT-connection. Then the following characteristics of this connection are equivalent:*

- (i) D is strong ($dT = 0$);
- (ii) D has a ∇ -parallel torsion;
- (iii) D is flat.

Theorem 19. ([15]). *Let (M, H, G) be an almost (H, G) -manifold from \mathcal{W}_{133} and D be the pHKT-connection. If D is flat or strong then (M, H, G) is ∇ -flat, isotropic-hyper-Kählerian (i.e. $\|\nabla J_\alpha\|^2 = 0$, $\alpha = 1, 2, 3$) and the torsion of D is isotropic (i.e. $\|T\|^2 = 0$).*

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