

SOME REMARKS ON A CLASS OF BOUNDARY VALUE PROBLEMS THAT INCLUDES THE St. VENANT PROBLEM

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НЯКОИ БЕЛЕЖКИ ЗА КЛАС ГРАНИЧНИ ЗАДАЧИ, ВКЛЮЧВАЩИ ПРОБЛЕМА НА St.VENANT

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Abstract. For solutions $u(x)$ of some boundary value problems defined in a bounded convex domain Ω of \mathbb{R}^N , $N \geq 2$, we show that their points of maximum are at distance from the boundary greater than $\frac{d}{2}$, where d is the inradius of Ω . Moreover for $N = 2$, a minimum principle for some combination of $u(x)$ and $|\nabla u|$ is established.

Key words: Minimum principles, second order elliptic boundary value problems

1. Introduction

This note addresses the following class of a boundary value problems defined in a bounded strictly convex domain $\Omega \subset \mathbb{R}^N$, $N \geq 2$

$$\Delta u + \alpha u + 1 = 0, x \in \Omega, u = 0, x \in \partial\Omega. \quad (1.1)$$

In (1.1) Δ is the Laplace operator and α is a constant $\in [0, \lambda_1)$, where λ_1 is the first eigenvalue of the fixed membrane problem defined as

$$\Delta \varphi_1 + \lambda_1 \varphi_1 = 0, \varphi_1 > 0, x \in \Omega, \quad \varphi_1 = 0, x \in \partial\Omega. \quad (1.2)$$

We note that (1.1) coincides with the St.Venant problem when $\alpha = 0$.

Problem (1.1) has been investigated by several authors [(Bandle 1976), (Kohler-Jobin 1981), (Payne, Philippin, Proytcheva 2007)].

With $\alpha < \lambda_1$, (1.1) admits a unique classical solution $u(x)$. In (Bandle 1976), Bandle shows that for $\alpha < \lambda_1$, $v(x) := \alpha u + 1$ is nonnegative in Ω , so that $\Delta u \leq 0$ in Ω ,

implying by the maximum principle that $u > 0$ in Ω . We note that $v(x)$ satisfies

$$\Delta v + \alpha v = 0, x \in \Omega, \quad v = 1, x \in \partial\Omega. \quad (1.3)$$

Let us assume contrariwise that $v < 0$ at some point $P \in \Omega$. Then there exists a region $\tilde{\Omega} \subset \Omega$ such that

$$v < 0 \text{ in } \tilde{\Omega}, \quad v = 0 \text{ on } \partial\tilde{\Omega}. \quad (1.4)$$

It then follows from Green's second identity that

$$0 = \int_{\tilde{\Omega}} v \Delta \tilde{\varphi}_1 - \tilde{\varphi}_1 \Delta v \, dx = \alpha - \tilde{\lambda}_1 \int_{\tilde{\Omega}} v \tilde{\varphi}_1 \, dx, \quad (1.5)$$

where $\tilde{\varphi}_1$ is the first eigenfunction and $\tilde{\lambda}_1$ the first eigenvalue of the fixed membrane problem in $\tilde{\Omega}$. (1.5) leads to the contradiction $\alpha = \tilde{\lambda}_1 > \lambda_1$.

In the second section of this note we show that for $\alpha \in \left(0, \frac{\pi^2}{4d^2}\right)$, the maxima of

$u(x)$ are located at distance greater than $\frac{d}{2}$ from the boundary $\partial\Omega$, where d is the inradius of Ω , i.e. the radius of the greatest ball contained in Ω . In the two-dimensional case $N = 2$, we derive in Section 3 an upper bound for $\min_{\partial\Omega} |\nabla u|^2$ in terms of u_{\max} , valid for $\alpha \in [0, \lambda_1]$.

2. Location of the maxima of $u(x)$

Since Ω is assumed bounded and strictly convex, it follows from (Finn 2008) p. 1343 that if $N = 2$, the level lines of $u(x)$ are convex, so that $u(x)$ has a unique critical point Q at which $u = u_{\max}$. However for $N \geq 3$ and $\alpha \neq 0$, the convexity of the level sets of $u(x)$ does not seem to be established. So we cannot exclude the possibility of several critical points of $u(x)$ if $N \geq 3$, $\alpha \neq 0$. In this section we establish the following result

Theorem 1. *If $\alpha \in \left(0, \frac{\pi^2}{4d^2}\right)$, where d is the inradius of Ω , then the maxima of $u(x)$ are*

at distance is greater than $\frac{d}{2}$ from the boundary $\partial\Omega$.

For the proof of Theorem 1, we make use of the following upper bound for $u(x)$ established in (Payne, Philippin, Proytcheva 2007).

$$u(x) \leq \frac{1}{\alpha} \left\{ \frac{\cos \left[\sqrt{\alpha} \left(d - x_0 - d - x \right) \right]}{\cos \left[\sqrt{\alpha} \left(d - x_0 \right) \right]} - 1 \right\}, x \in \Omega. \quad (2.1)$$

In (2.1), $d(x)$ is the distance from $x \in \Omega$ to $\partial\Omega$, and x_0 is any point where $u(x)$ takes its maximum value. From the inequality

$$\left(\frac{\pi^2}{4d^2} \right) < \lambda_1 \quad (2.2)$$

established for convex Ω by Hersch in (Hersch 1960) for $N = 2$, and by Sperb (Sperb 1981) for $N \geq 2$, it follows that $u(x) > 0$ in Ω as already mentioned.

Inequality (2.1) then implies

$$\cos \left[\sqrt{\alpha} (d(x_0) - d(x)) \right] > \cos \sqrt{\alpha} d(x_0), \quad x \in \Omega \quad (2.3)$$

$$\text{i.e.} \quad |d(x_0) - d(x)| < d(x_0), \quad x \in \Omega \quad (2.4)$$

$$\text{i.e.} \quad d(x_0) > \frac{1}{2} d(x), \quad x \in \Omega. \quad (2.5)$$

Since (2.5) holds for all $x \in \Omega$, we obtain the desired inequality

$$d(x_0) > \frac{1}{2} \max_{x \in \Omega} d(x) = \frac{1}{2} d. \quad (2.6)$$

3. An upper bound for $\min_{\partial\Omega} |\nabla u|^2$

In (Payne, Philippin, Proytcheva 2007) the authors showed that for Ω bounded convex in \mathbb{R}^N , $N \geq 2$ the auxiliary function $\chi(x)$, defined as

$$\chi(x) := |\nabla u|^2 + \alpha u^2 + 2u, \quad \alpha = \text{const} \in (0, \lambda_1) \quad (3.1)$$

takes its maximum at a critical point of $u(x)$. In this section we want to show that in the particular case $N = 2$, $\chi(x)$ takes its minimum value at some point on the boundary $\partial\Omega$. This leads to the following result:

Theorem 2. *Let Ω be a bounded strictly convex domain in \mathbb{R}^2 . Then we have*

$$\min_{\partial\Omega} |\nabla u|^2 \leq \chi(x) := |\nabla u|^2 + \alpha u^2 + 2u, \quad x \in \Omega. \quad (3.2)$$

In particular

$$\min_{\partial\Omega} |\nabla u|^2 \leq \alpha u_{\max}^2 + 2u_{\max}. \quad (3.3)$$

For the proof of Theorem 2, we show under the assumptions of Theorem 2, that

$\chi(x)$ satisfies an appropriate differential equation. For convenience we write $u_{,k} := \frac{\partial u}{\partial x_k}$

and adopt the summation convention on repeated indices. With these conventions we have for

instance

$$|\nabla u|^2 = \sum_{k=1}^2 \left(\frac{\partial u}{\partial x_k} \right)^2 = u_{,k} u_{,k}, \quad \Delta u = \sum_{k=1}^2 \frac{\partial^2 u}{\partial x_k^2} = u_{,kk}$$

$$\sum_{i=1}^2 \sum_{k=1}^2 \left(\frac{\partial^2 u}{\partial x_i \partial x_k} \right) = u_{,ik} u_{,ik}.$$

Differentiating (3.1) and making use of (1.1), we obtain

$$\chi_{,k} = 2u_{,ik} u_{,i} + 2u_{,k} \alpha u + 1 = 2u_{,ik} u_{,i} - 2u_{,k} \Delta u \quad (3.4)$$

$$\begin{aligned} \Delta \chi &= 2u_{,ik} u_{,ik} + 2u_{,k} \Delta u_{,i} - 2u_{,k} \Delta u_{,i} - 2 \Delta u_{,k}^2 \\ &= 2u_{,ik} u_{,ik} - 2 \Delta u_{,k}^2. \end{aligned} \quad (3.5)$$

Making use of the following identity

$$\frac{1}{2} |\nabla u|^2 u_{,ik} u_{,ik} - \Delta u_{,k}^2 = u_{,ik} u_{,k} u_{,ij} u_{,j} - \Delta u u_{,ik} u_{,i} u_{,k} \quad (3.6)$$

valid in \mathbb{R}^2 only, we obtain

$$\Delta \chi = 4 |\nabla u|^{-2} u_{,ik} u_{,k} u_{,ij} u_{,j} - \Delta u u_{,ik} u_{,i} u_{,k}. \quad (3.7)$$

From (3.4) rewritten as

$$u_{,ik} u_{,i} = u_{,k} \Delta u + \frac{1}{2} \chi_{,k} \quad (3.8)$$

we compute

$$u_{,ik} u_{,i} u_{,jk} u_{,j} = \Delta u_{,k}^2 |\nabla u|^2 + u_{,k} \chi_{,k} + \frac{1}{4} |\nabla \chi|^2 \quad (3.9)$$

$$u_{,ik} u_{,i} u_{,k} = \Delta u |\nabla u|^2 + \frac{1}{2} u_{,k} \chi_{,k}. \quad (3.10)$$

It follows from (3.7), (3.9), (3.10) that $\chi(x)$ satisfies the differential equation:

$$\Delta \chi - |\nabla u|^{-2} \nabla \chi \cdot 2\Delta u \nabla u + \nabla \chi = 0, \quad x \in \Omega \setminus Q, \quad (3.11)$$

where Q is the unique critical point of u . It then follows from Hopf's first maximum principle (Hopf 1927) that $\chi(x)$ takes its maximum and minimum values either on $\partial\Omega$ or at Q .

Finally the outward normal derivative of $\chi(x)$ on $\partial\Omega$ is given by

$$\frac{\partial \chi}{\partial n} = -2K(x) \frac{\partial u}{\partial n}^2 \leq 0, \quad x \in \partial\Omega \quad (3.13)$$

where $K(x)$ is the curvature of $\partial\Omega$. It then follows from Hopf's second maximum principle (Hopf 1927) that $\chi(x)$ cannot take its maximum value on $\partial\Omega$. We then

conclude that $\chi(x)$ must take its maximum value at the critical point Q , and its minimum value on $\partial\Omega$. This completes the proof of Theorem 2.

We note that the inequalities in Theorem 2 are not sharp in the sense that there is no convex plane domain Ω for which we have $\chi(x) \equiv \text{const}$.

Indeed, suppose that $\chi(x) \equiv \text{const}$ in Ω . Then the identity (3.6) takes the form

$$u_{,ik} u_{,ik} - \Delta u^2 = 0, \quad x \in \Omega \quad (3.13)$$

in view of (3.9), (3.10) with $\nabla\chi = 0$. (3.13) may be rewritten as

$$\Delta u u_{,k} - \frac{1}{2} |\nabla u|^2_{,k} = 0, \quad x \in \Omega. \quad (3.14)$$

It then follows from the divergence theorem that

$$\int_{\partial\Omega} \Delta u \frac{\partial u}{\partial n} - \frac{1}{2} \frac{\partial}{\partial n} |\nabla u|^2 \, ds = \int_{\partial\Omega} K(x) \frac{\partial u}{\partial n} \, ds = 0, \quad (3.14)$$

which cannot hold since $K(x) \geq 0$ and $\frac{\partial u}{\partial n} < 0$ on $\partial\Omega$ by Hopf's second maximum principle.

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